



FINDING A BETTER WAY

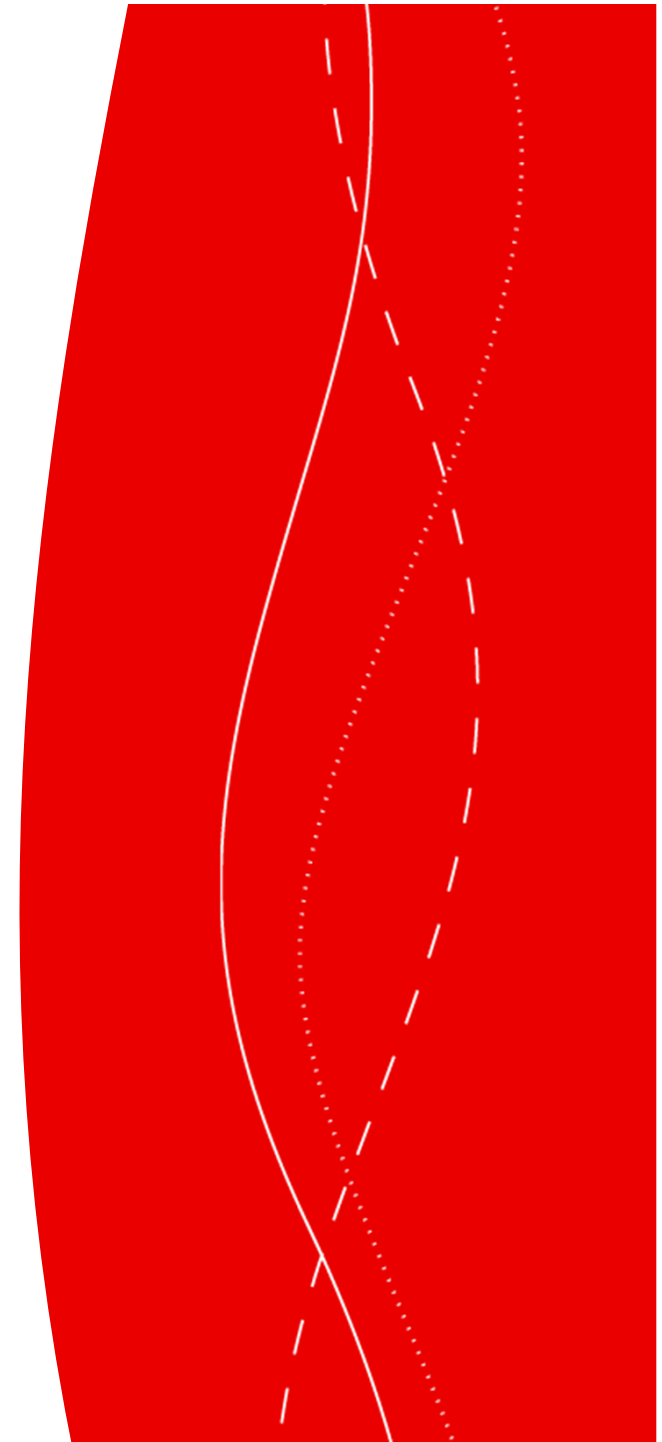
A Field Test of Eye Tracking Systems with One and Three Cameras

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Introduction

- Advanced Driver Assistance Systems such as LDW and FCW are potential life savers
- Robustness, false warnings and resulting acceptance may be an issue
- Improvements can be achieved by integrating driver state information as a data source
- A key component in non-obtrusive driver state assessment is eye tracking



Remote eye tracking

- To assess where a driver looks we need to measure his/her eye movements
- In a naturalistic driving study or in everyday driving situations, the eye tracker needs to be remote
- Multi-camera systems have better performance, but ...
- ... the commercial use of eye trackers is limited to 1-camera systems
 - easier to fit into the cockpit
 - lower-priced
- However:
 - limited coverage -> tracking is lost for larger gaze angles
 - gaze direction assessment within a given coordinate system is not possible



Aim and scope

- One-camera systems are often used in large-scale driving studies (e.g. euroFOT and SHRP2)
- We need to understand how one-camera systems perform in real-life conditions to be able to interpret the results
- Parallel acquisition of data from a high-end three-camera system and an embedded one-camera system intended for commercial use.
- Given the best possible prerequisites, how similar are data from the two systems?



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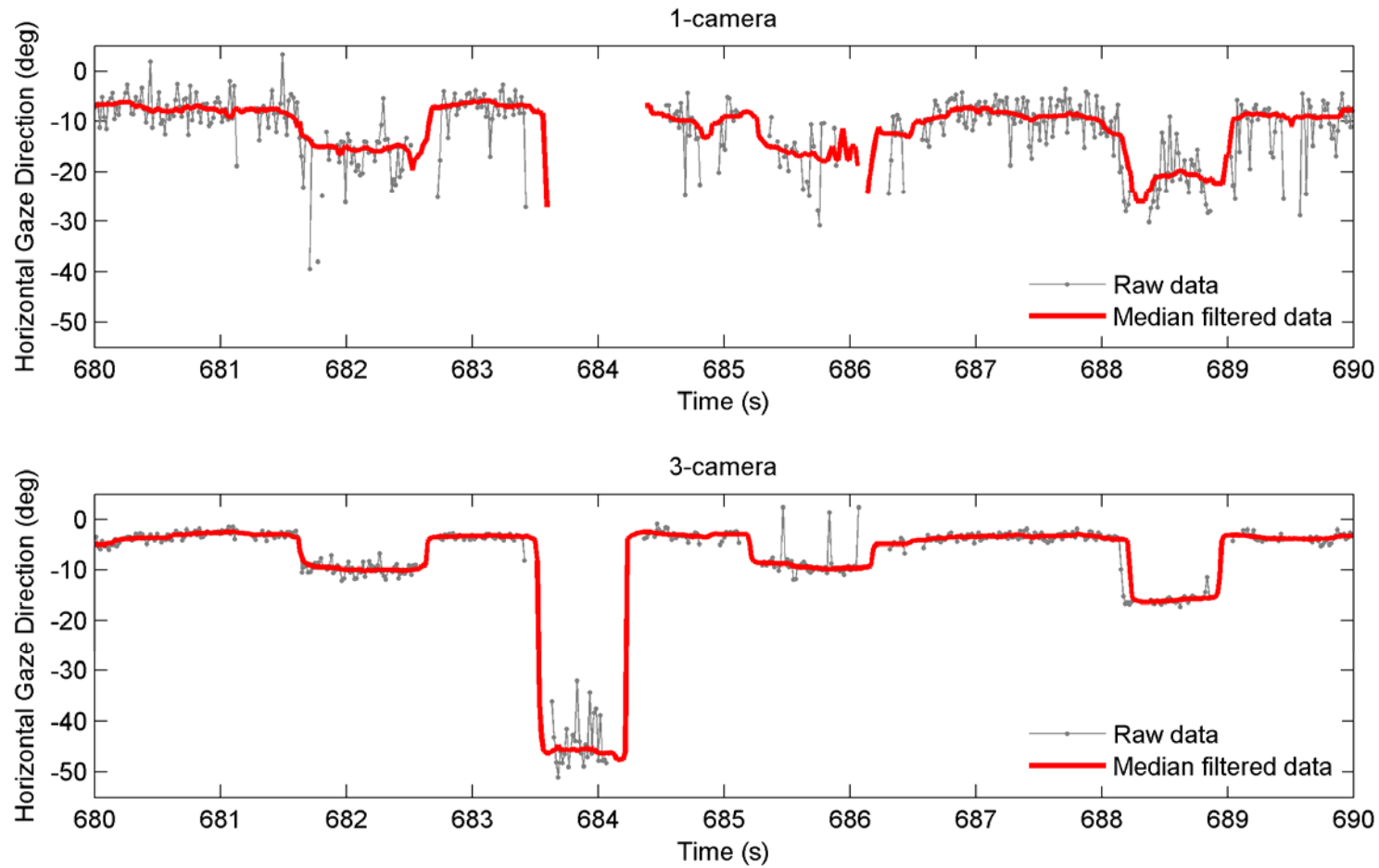


Methodology

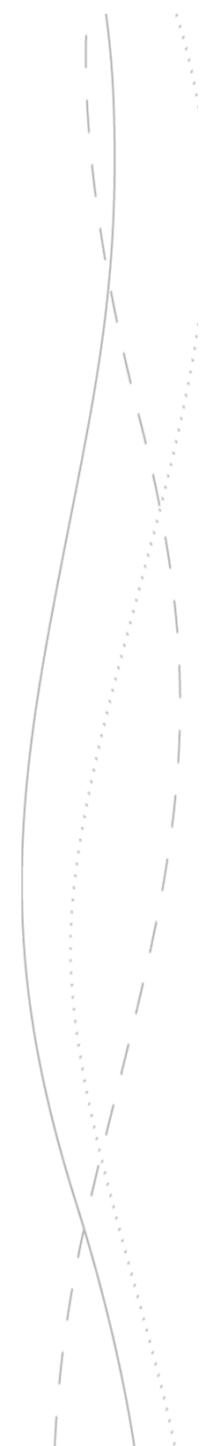
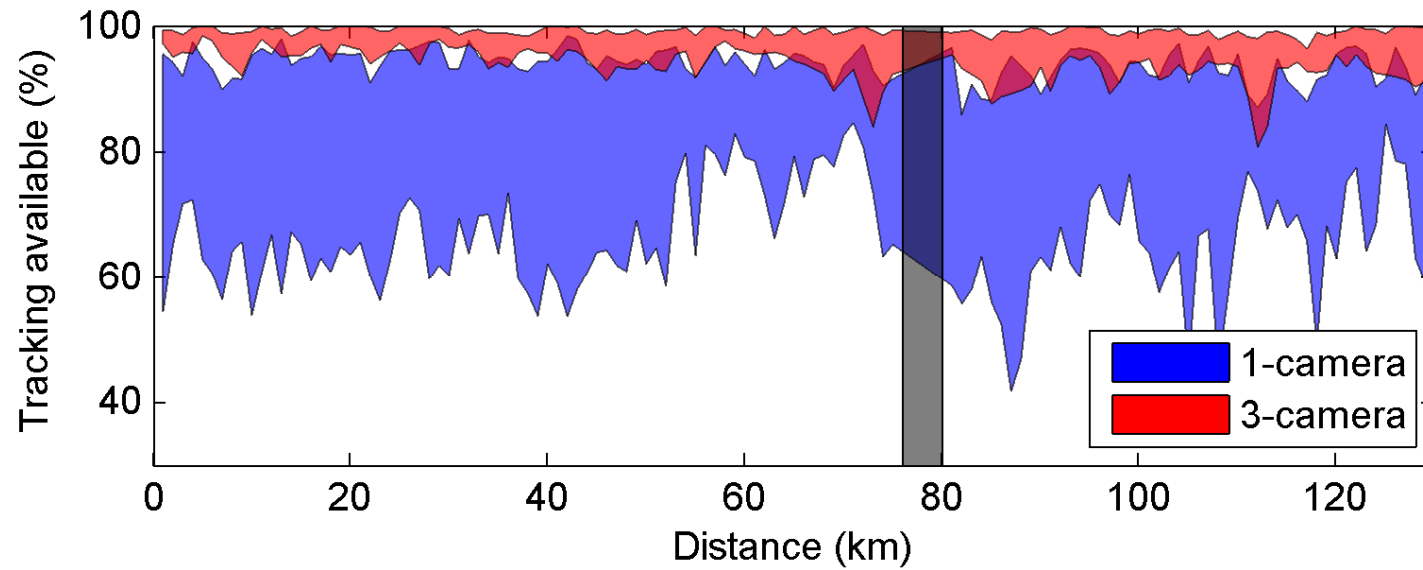
- Eight women and ten men participated in the study, 30 – 60 years old
- 80 km section of the motorway E4
- No glasses, no make-up and no beard to avoid interference with the eye trackers
- Participants were not allowed to speak or engage in any other secondary task
- SmartEye experts set up the eye trackers before each trip



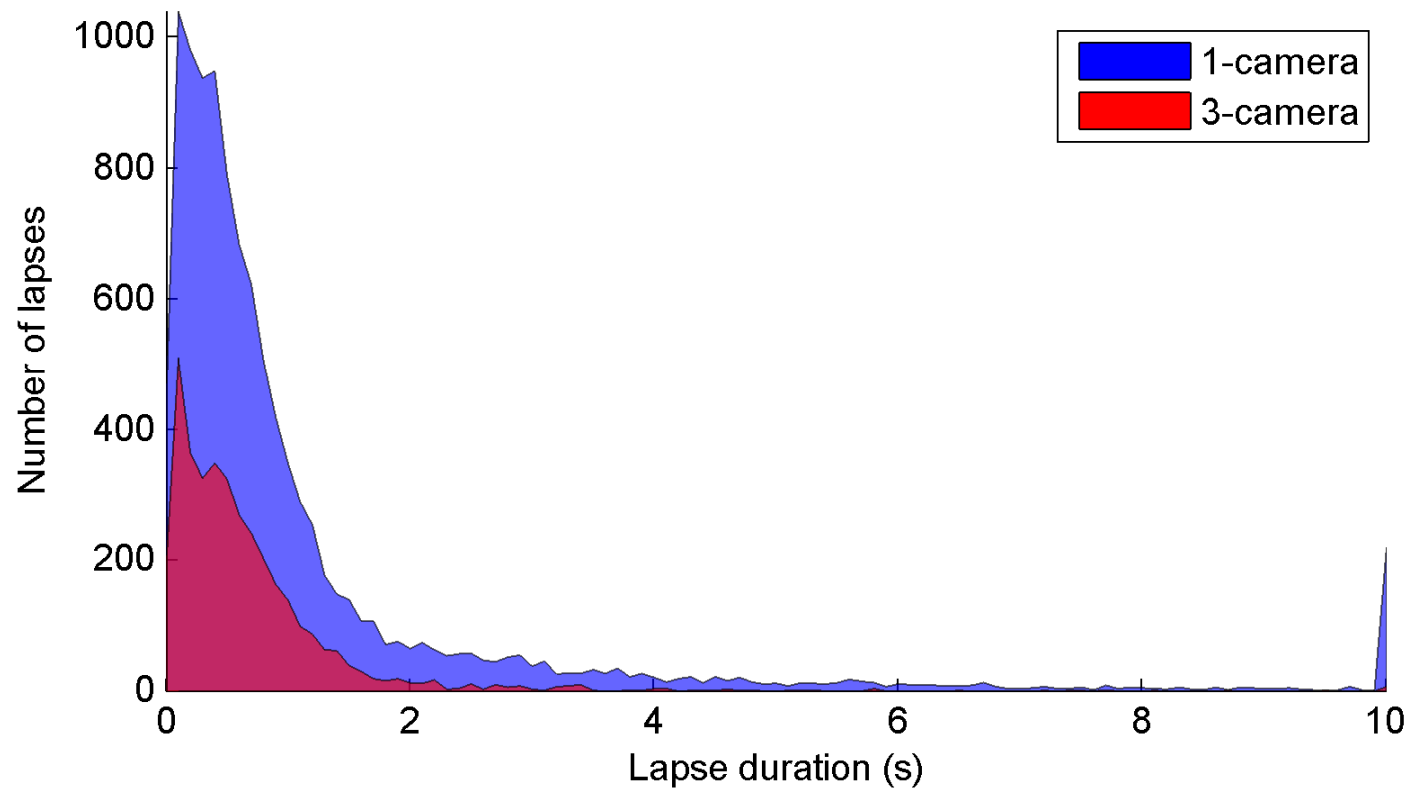
Results, example of raw data



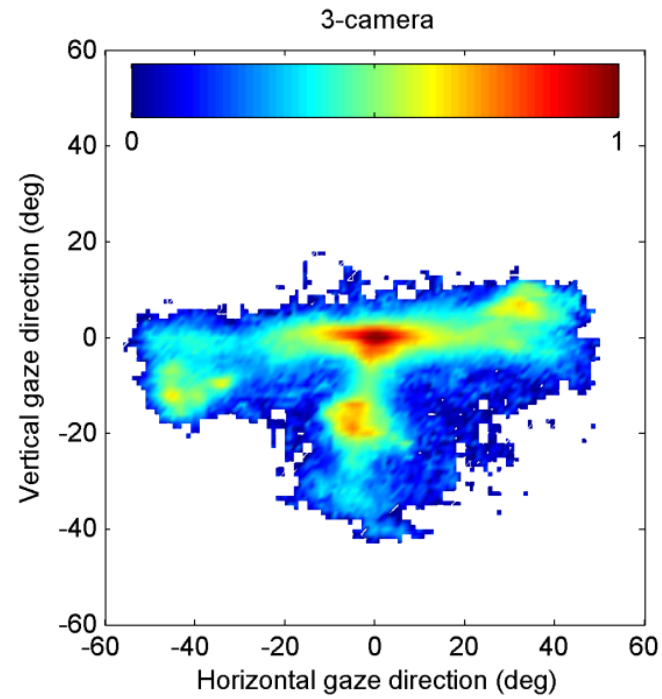
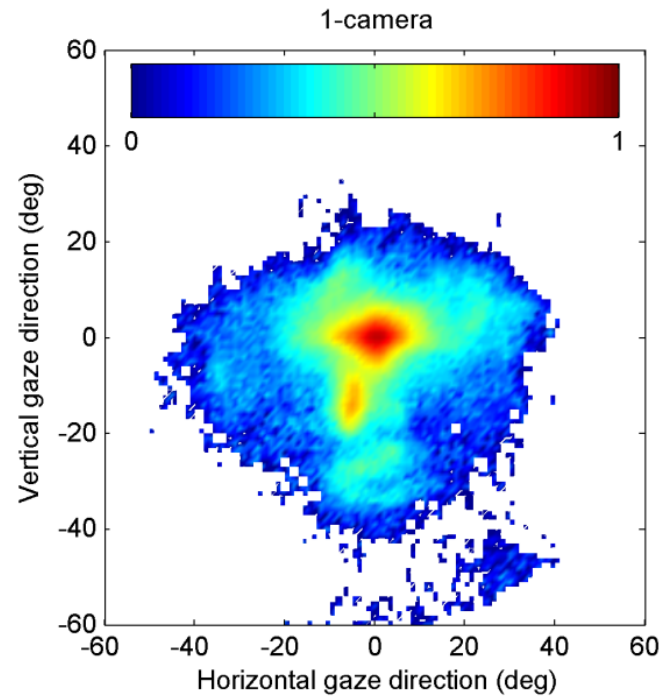
Results, available tracking



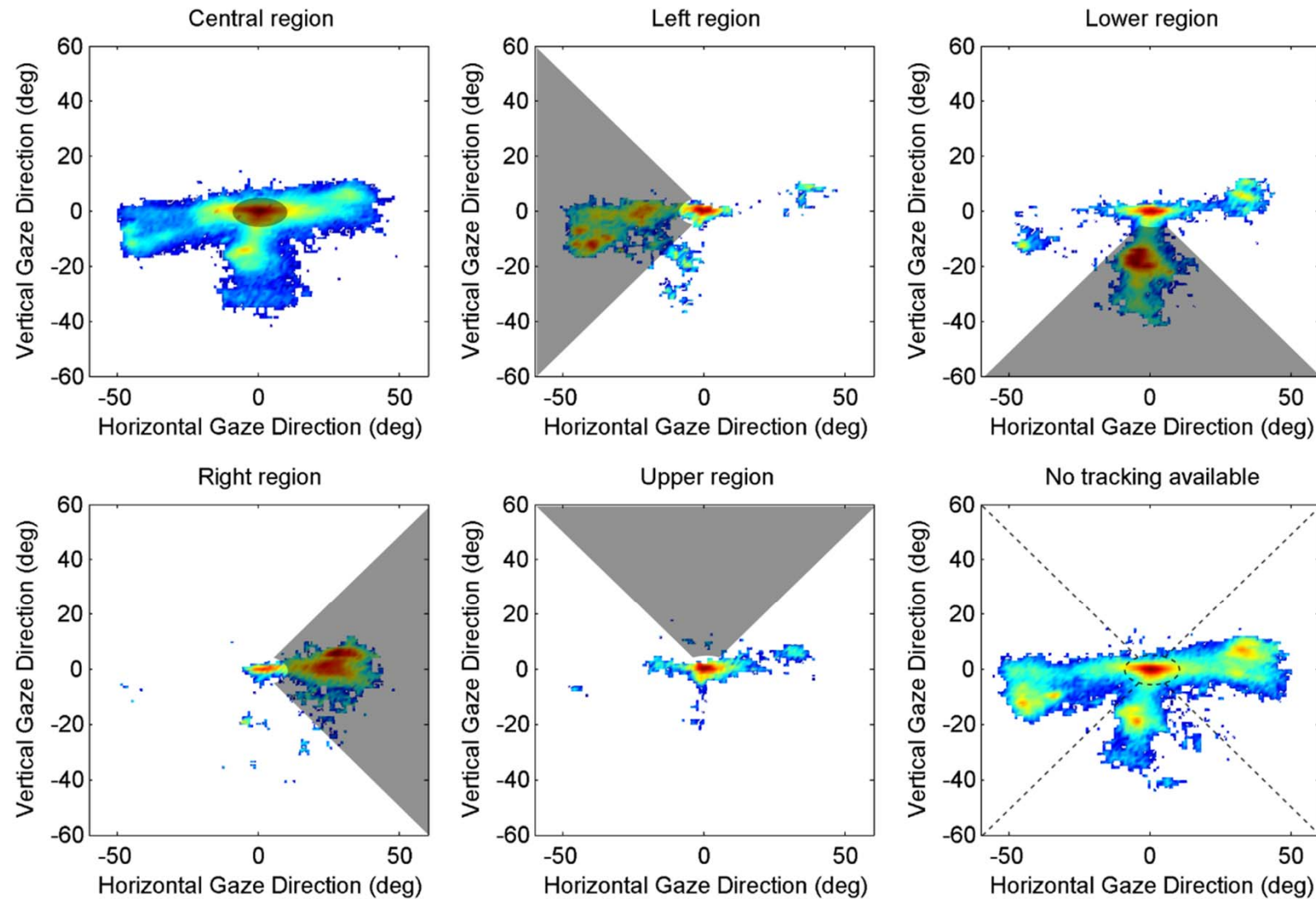
Results, missing data distribution



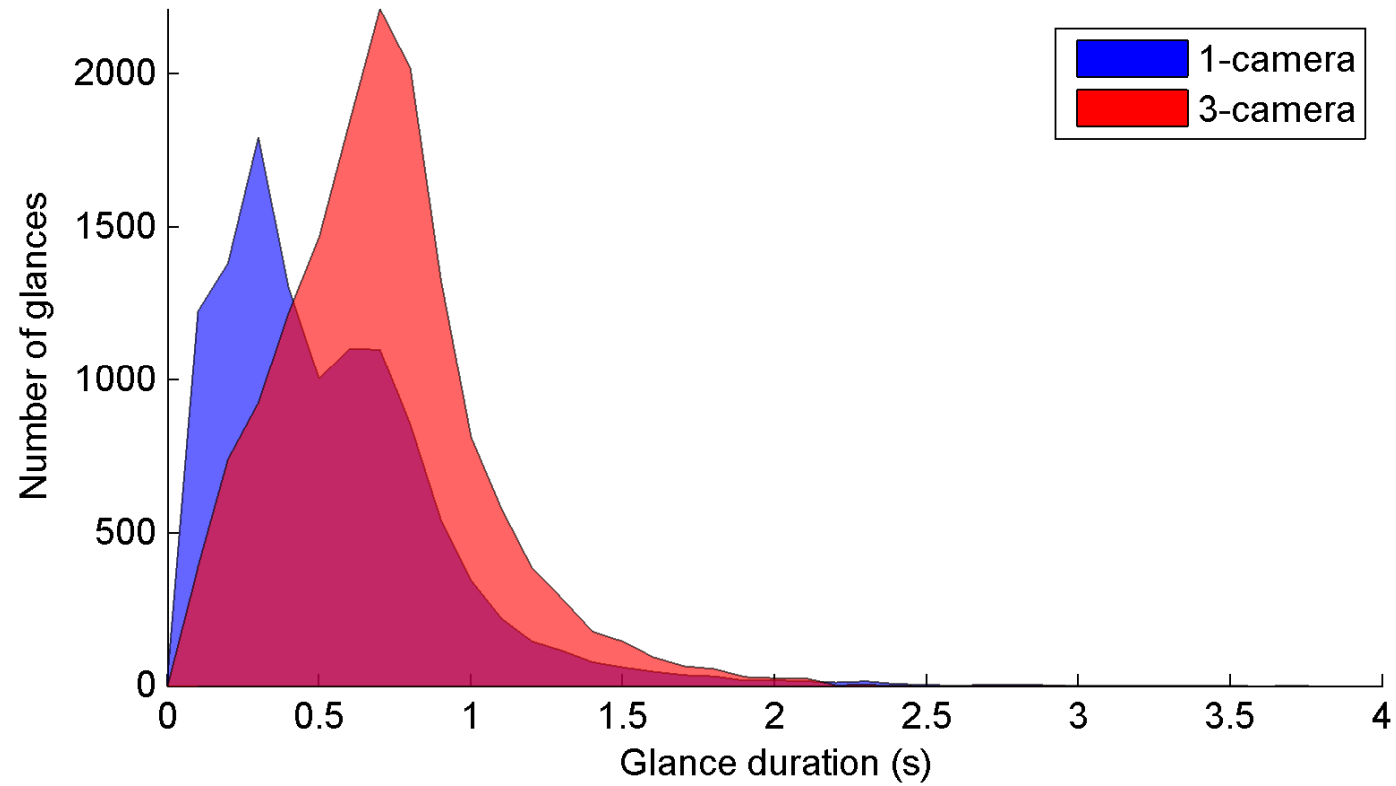
Results, data distribution



Results, correspondance between systems



Results, Glance duration



Conclusions

- The 3-camera system shows better performance with respect to data availability, working envelope and accuracy
- Data from the 1-camera system often disagree with 3-camera data
- A big improvement for future 1-camera systems would be increased reliability and availability in the forward direction so that missing values can be interpreted as either a blink or a gaze outside the coverage of the camera with help of intelligent algorithms
- As of now, use of the 1-camera system requires special handling of lapses



Thank you for listening!

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